General geometry of belief function combination

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Abstract. In this paper we build on previous work on the geometry of
Dempster's rule to investigate the geometric behaviour of various other
combination rules, including Yager's, Dubois', and disjunctive combina-
tion, starting from the case of binary frames of discernment. Believabil-
ity measures for unnormalised belief functions are also considered. A
research programme to complete this analysis is outlined.

Keywords: Geometry · Yager's and Dubois' combination · conjunctive
and disjunctive combination · unnormalised belief functions.

1 Introduction

In the geometric approach to uncertainty and belief function theory [3], belief
measures are represented as points of a convex space, termed *belief space* $\mathcal{B}$
[2]. In a series of papers, in particular, this author studied the behaviour of
Dempster's rule of combination in this geometric setting [1]. An earlier analysis
of Dempster's rule on binary domains can be found in [6].

In this work, we start to extend this geometric analysis to several other
major combination operators, including Yager's [10] and Dubois' rules, but also
the disjunctive operator [8]. The final objective of the research programme is
a comparative geometric analysis of combination rules, which would eventually
allow us to describe the 'cone' of possible future belief states under stronger
or weaker assumptions on reliability and independence of sources, associated
with conjunctive and disjunctive combination. The bulk of the analysis focusses
on standard, normalised belief functions – towards the end, however, we also
consider unnormalised belief functions [9] and provide some preliminary results.

We start by giving a general definition of *conditional subspace* (cfr. [3], Chap-
ter 8), as the set of possible future states under a given combination rule.

Definition 1. *Given a belief function (BF) $Bel \in \mathcal{B}$ we call* conditional sub-
space $\langle Bel \rangle_{\odot}$ *the set of all $\odot$ combinations of Bel with any other BF Bel′ defined
on the same frame, where $\odot$ is an arbitrary combination rule, assuming their
combination exists:* $\langle Bel \rangle_{\odot} \doteq \left\{ Bel \odot Bel', \ Bel' \in \mathcal{B} \ s.t. \ \exists \left(Bel \odot Bel' \right) \right\}$.

Our analysis will be conducted on binary spaces, and used to formulate con-
jectures on the case of general frames of discernment. We will first recall the
necessary notions of the geometric approach to belief theory in Section 2. We

will consider Yager's and Dubois' rules in Section 3, disjunctive combination in Section 4, to cover the behaviour of unnormalised BFs in Section 5. We will draw some verdicts and outline future work in our Conclusions.

2 Belief functions and their geometry

Belief functions. A *basic probability assignment* (BPA) [7] over a discrete set (frame) Θ is a function $m : 2^\Theta \to [0, 1]$ defined on $2^\Theta = \{A \subseteq \Theta\}$ such that: $m(\emptyset) = 0$, $\sum_{A \subset \Theta} m(A) = 1$. The *belief function* (BF) associated with a BPA $m : 2^\Theta \to [0, 1]$ is the function $Bel : 2^\Theta \to [0, 1]$ defined as: $Bel(A) = \sum_{B \subseteq A} m(B)$. The elements of the power set 2^Θ associated with non-zero values of m are called the *focal elements* of m. For each subset ('event') $A \subset \Theta$ the quantity $Bel(A)$ is called the *degree of belief* that the outcome lies in A. *Dempster's combination* $Bel_1 \oplus Bel_2$ of two belief functions on Θ is the unique BF there with as focal elements all the non-empty intersections of focal elements of Bel_1 and Bel_2, and basic probability assignment: $m_\oplus(A) = \frac{m_\cap(A)}{1 - m_\cap(\emptyset)}$, where $m_\cap(A) = \sum_{B \cap C = A} m_1(B) m_2(C)$ and m_i is the BPA of the input BF Bel_i.

Belief space. Given a frame of discernment Θ, a BF Bel is specified by its $N - 2$ belief values $\{Bel(A), \emptyset \subsetneq A \subsetneq \Theta\}$, $N \doteq 2^{|\Theta|}$, and can then be represented as a point of $\mathbb{R}^{N-2}$. The *belief space* [1, 2] associated with Θ is the set of points $\mathcal{B}$ of $\mathbb{R}^{N-2}$ which correspond to proper belief functions. It can be proven that the belief space $\mathcal{B}$ is the convex closure Cl of all the vectors associated with *categorical* BFs Bel_A (such that $m(A) = 1$): $\mathcal{B} = Cl(Bel_A, \emptyset \subsetneq A \subseteq \Theta) = \{\sum_{\emptyset \subsetneq A \subseteq \Theta} \alpha_A Bel_A, \alpha_A \geq 0 \forall A, \sum_A \alpha_A = 1\}$, an $(N - 2)$-dimensional *simplex*.
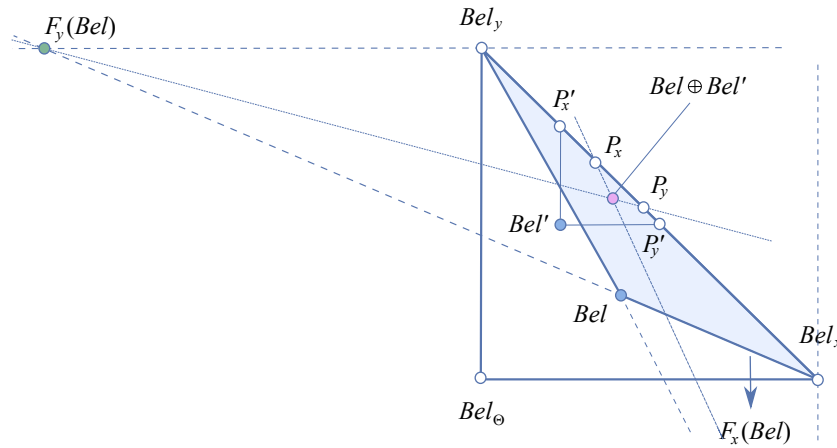
Fig. 1. Graphical construction of Dempster's combination in the binary belief space.

Geometry of Dempster's rule. In [3] we proved that the conditional subspace $\langle Bel \rangle$ under Dempster's combination is $\langle Bel \rangle = Cl\{Bel \oplus Bel_A, A \subseteq \mathcal{C}_{Bel}\}$, where $\mathcal{C}_{Bel}$ is the union of the focal elements of Bel (see Figure 1, in light blue, for the binary case $\Theta_2 = \{x, y\}$). Dempster's combination of a BF Bel with

another BF Bel' with mass m' describes, for $m'(y) \in \mathbb{R}^1$, a straight line in the belief space, except the point with coordinates: $F_x(Bel) = [1, -\frac{m(\Theta_2)}{m(x)}]'$,[2] which coincides with the limit of $Bel \oplus Bel'$ for $m'(y) \to \pm\infty$. This is true for every value of $m'(x) \in [0, 1]$. Indeed, all the collections of Dempster's sums $Bel \oplus Bel'$ with $m'(x) = k = const$ have a common intersection at the point $F_x(Bel)$, which is located outside the belief space. In the same way, this holds for the sets $\{Bel \oplus Bel' : m'(y) = l = const\}$, which each form a distinct line passing through a twin point: $F_y(Bel) = [-\frac{m(\Theta)}{m(y)}, 1]'$.

We call $F_x(Bel), F_y(Bel)$ the *foci* of the conditional subspace $\langle Bel \rangle$.

Dempster's rule thus admits an elegant geometric construction in the belief space, illustrated, for the binary case, in Figure 1.

Algorithm 1 Dempster's rule: geometric construction in $\mathcal{B}_2$.

1: **procedure** GEODEMPSTER2(Bel, Bel')
2:     compute the foci $F_x(Bel), F_y(Bel)$ of the conditional subspace $\langle Bel \rangle$;
3:     project Bel' onto $\mathcal{P}$ along the orthogonal directions, obtaining P'_x and P'_y;
4:     combine Bel with P'_x and P'_y (a much simpler operation) to get P_x and P_y;
5:     draw the lines $\overline{P_x F_x(Bel)}$ and $\overline{P_y F_y(Bel)}$: their intersection is the desired orthogonal sum $Bel \oplus Bel'$.
6: **end procedure**

These notions can be naturally extended to finite frames with an arbitrary number $|\Theta|$ of elements ([3], Chapter 8).

3   Geometry of Yager's and Dubois' rules

Yager's and Dubois' rules. Yager's rule [10] is based on the view that conflict is generated by non-reliable information sources. In response, the conflicting mass (here denoted by $m_\cap(\emptyset)$) is re-assigned to the whole frame of discernment Θ:

$$m_{\widehat{Y}}(A) = \begin{cases} m_\cap(A) & \emptyset \neq A \subsetneq \Theta \\ m_\cap(\Theta) + m_\cap(\emptyset) & A = \Theta. \end{cases} \tag{1}$$

The combination operator proposed by Dubois and Prade [5] comes from applying the *minimum specificity* principle to the cases in which the focal elements B, C of two input BFs do not intersect, and assigns their product mass to $B \cup C$:

$$m_D(A) = m_\cap(A) + \sum_{B \cup C = A, B \cap C = \emptyset} m_1(B) m_2(C). \tag{2}$$

Analysis on binary frames. On binary frames, $\Theta = \{x, y\}$ Yager's rule (1) and Dubois' rule (2) coincide, as the only conflicting focal elements are $\{x\}$ and

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[1] For Dempster's rule can be extended to pseudo belief functions.
[2] We write $m(x)$ instead of $m(\{x\})$, Bel_x rather than $Bel_{\{x\}}$ to simplify the notation.
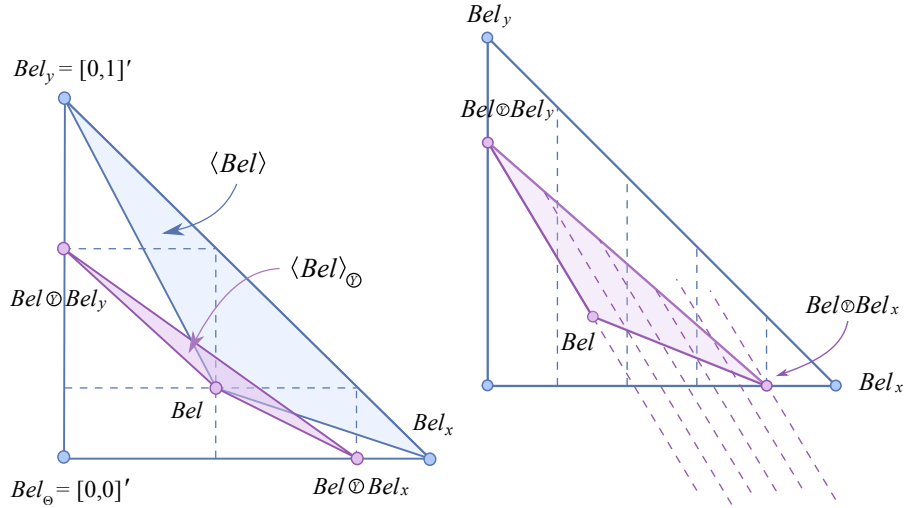
$\{y\}$, whose union is Θ itself:

$$
\begin{aligned}
m_{\textcircled{Y}}(x) &= m_1(x)(1 - m_2(y)) + m_1(\Theta)m_2(x), \\
m_{\textcircled{Y}}(y) &= m_1(y)(1 - m_2(x)) + m_1(\Theta)m_2(y), \\
m_{\textcircled{Y}}(\Theta) &= m_1(x)m_2(y) + m_1(y)m_2(x) + m_1(\Theta)m_2(\Theta).
\end{aligned}
\tag{3}
$$

Using (3) we can easily show that:

$$
Bel\textcircled{Y}Bel_x = [m(x) + m(\Theta), 0, m(y)]'; \quad Bel\textcircled{Y}Bel_y = [0, m(y) + m(\Theta), m(x)]';
$$
$$
Bel\textcircled{Y}Bel_\Theta = Bel = [m(x), m(y), m(\Theta)],
\tag{4}
$$

once adopting the vector notation $Bel = [Bel(x), Bel(y), Bel(\Theta)]'$.
The conditional subspace $\langle Bel \rangle_{\textcircled{Y}}$ (Figure 2 (left)) is thus the convex closure of the points (4): $\langle Bel \rangle_{\textcircled{Y}} = Cl(Bel, Bel\textcircled{Y}Bel_x, Bel\textcircled{Y}Bel_y)$.

Fig. 2. (Left) Conditional subspace $\langle Bel \rangle_{\textcircled{Y}}$ for Yager's (and Dubois') combination rule on a binary frame $\Theta = \{x, y\}$. Dempster's $\langle Bel \rangle$ is also shown for comparison. (Right) In Yager's combination, the images of constant mass loci (dashed blue segments) do not converge to a focus, but form parallel lines (dashed purple, cfr. Figure 1).

Comparing (3) with (4), it is easy to see that

$$
Bel_1\textcircled{Y}Bel_2 = m_2(x)\big(Bel_1\textcircled{Y}Bel_x\big) + m_2(y)\big(Bel_1\textcircled{Y}Bel_y\big) + m_2(\Theta)\big(Bel_1\textcircled{Y}Bel_\Theta\big),
$$

i.e., the simplicial coordinates of Bel_2 in the binary belief space $\mathcal{B}_2$ and of the Yager combination $Bel_1\textcircled{Y}Bel_2$ in the conditional subspace $\langle Bel_1 \rangle_{\textcircled{Y}}$ coincide. We can then conjecture the following.

Conjecture 1. Yager combination and *affine combination* commute. Namely:

$$
Bel\textcircled{Y}\left(\sum_i \alpha_i Bel_i\right) = \sum_i \alpha_i Bel\textcircled{Y}Bel_i, \quad \alpha_i \in \mathbb{R}\ \forall i, \sum_i \alpha_i = 1.
$$

As commutativity is the basis for the geometric analysis of Dempster's rule [1], this opens the way for a similar geometric construction for Yager's rule. However, as shown in Figure 2 (right), images of constant mass loci under Yager's rule are parallel, and there are no foci. From (3) it follows that:

$$\lim_{m_2(y)\to-\infty} \frac{m_{\textcircled{y}}(y)}{m_{\textcircled{y}}(x)} = \frac{m_1(y)(1-m_2(x))+m_1(\Theta)m_2(y)}{m_1(x)(1-m_2(y))+m_1(\Theta)m_2(x)} = -\frac{m_1(\Theta)}{m_1(x)},$$

and similarly for the loci with $m_2(y) = const.$

Nevertheless, as we will rigorously prove in upcoming work, Yager's combination also admits a geometric construction based on intersecting linear spaces which are images of constant mass loci.

4 Geometry of disjunctive combination

Disjunctive combination [8] is the natural, cautious dual of Dempster's combination. The operator follows from the assumption that the consensus between two sources of evidence is best represented by the union of the supported hypotheses, rather than by their intersection. An algebraic analysis of disjunctive combination on binary frames, in the form of 'Dempster semigroups', is due to Daniel [4]. Combination results are there visualised in a way similar to that presented here, although the focus is not on the geometry.
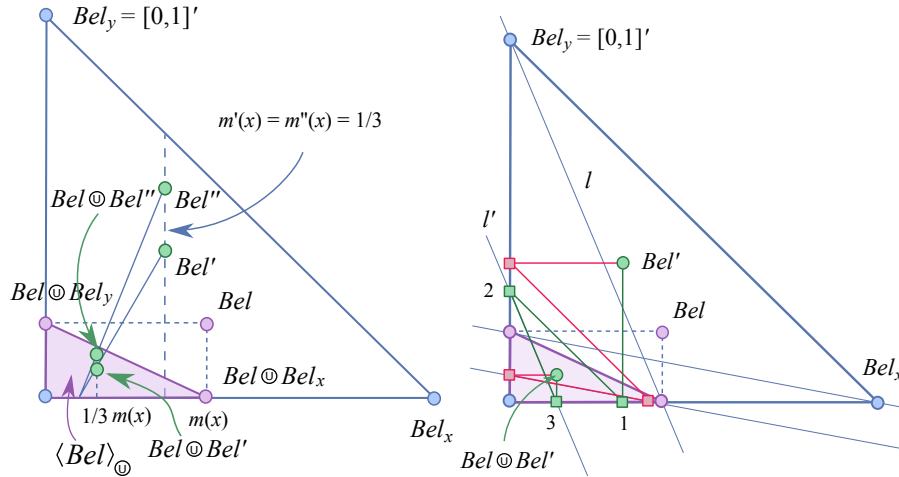
Fig. 3. (Left) Conditional subspace $\langle Bel \rangle_{\textcircled{\cup}}$ for disjunctive combination on a binary frame. (Right) Geometric construction for the disjunctive combination of two belief functions Bel, Bel' on a binary frame.

Conditional subspace. By definition: $m_{\textcircled{\cup}}(x) = m_1(x)m_2(x)$, $m_{\textcircled{\cup}}(y) = m_1(y)m_2(y)$, $m_{\textcircled{\cup}}(\Theta) = 1 - m_1(x)m_2(x) - m_1(y)m_2(y)$. Hence, in the usual vector notation:

$$Bel \textcircled{\cup} Bel_x = [m(x), 0, 1-m(x)]'; \quad Bel \textcircled{\cup} Bel_y = [0, m(y), 1-m(y)]'; \qquad (5)$$
$$Bel \textcircled{\cup} Bel_\Theta = Bel_\Theta.$$

The conditional subspace $\langle Bel \rangle_{\textcircled{U}}$ is thus the convex closure of the points (5):

$$\langle Bel \rangle_{\textcircled{U}} = Cl(Bel, Bel\textcircled{U}Bel_x, Bel\textcircled{U}Bel_y)$$

(see Figure 3). As in Yager's case: $Bel\textcircled{U}[\alpha Bel' + (1-\alpha)Bel''] = [m(x)(\alpha m'(x) + (1-\alpha)m''(x)), m(y)(\alpha m'(y) + (1-\alpha)m''(y))]' = \alpha Bel\textcircled{U}Bel' + (1-\alpha)Bel\textcircled{U}Bel''$, i.e., $\textcircled{U}$ *commutes with affine combination*, at least in the binary case.

   Pointwise behaviour. As in Yager's case, for disjunctive combination images of constant mass loci are parallel to each other. Actually, they are parallel to the corresponding constant mass loci and the coordinate axes (observe in Figure 3 (left) the locus $m'(x) = m''(x) = 1/3$ and its image in the conditional subspace $\langle Bel \rangle_{\textcircled{U}}$, with coordinate $1/3m(x)$). We can prove the following.

Theorem 1. *In the binary case $\Theta = \{x, y\}$, all the lines joining Bel' and $Bel\textcircled{U}Bel'$ for any $Bel' \in \mathcal{B}$ intersect at the point:*

$$\overline{m(x)} = m'(x)\frac{m(x) - m(y)}{1 - m(y)}, \quad \overline{m(y)} = 0. \qquad (6)$$

Proof. Recalling the equation of the line joining two points (χ_1, υ_1) and (χ_2, υ_2) of $\mathbb{R}^2$, with coordinates (χ, υ): $(\upsilon - \upsilon_1) = \frac{\upsilon_2 - \upsilon_1}{\chi_2 - \chi_1}(\chi - \chi_1)$, we can identify the line joining Bel' and $Bel\textcircled{U}Bel'$ as:

$$(\upsilon - m'(y)) = \frac{m(y)m'(y) - m'(y)}{m(x)m'(x) - m'(x)}(\chi - m'(x)).$$

Its intersection with $\upsilon = 0$ is the point (6), which does not depend on $m'(y)$ (i.e., on the vertical location of Bel' on the constant mass loci).

   A geometric construction for the disjunctive combination $Bel\textcircled{U}Bel'$ of two BFs in $\mathcal{B}_2$ is provided by simple trigonometric arguments (Figure 3 (right)):

1. starting from Bel', find its orthogonal projection onto the horizontal axis, with coordinate $m'(x)$ (point 1);
2. draw the line with slope 45° passing through such projection, and intersect it with the vertical axis, at coordinate $\upsilon = m'(x)$ (point 2);
3. finally, take the line l passing through Bel_y and the orthogonal projection of Bel onto the horizontal axis, and draw a parallel one l' through point 2 – its intersection with the horizontal axis (point 3) is the x coordinate $m(x)m'(x)$ of the desired combination.

A similar construction (in magenta) allows us to locate the y coordinate of the combination (as shown in Figure 3 (right)).

5   Combination of unnormalised belief functions

In the case of unnormalised belief functions (those for which $m(\emptyset) \geq 0$, UBFs [9]), Dempster's rule is replaced by *conjunctive combination*: $m_{\textcircled{\cap}}(A) \doteq m_{\cap}(A)$. Disjunctive combination itself needs to be reassessed for UBFs as well.

In the unnormalised case, a distinction exists between the *belief* measure $Bel(A) \doteq \sum_{\emptyset \neq B \subseteq A} m(B)$ and the *believability* (in Smets' terminology) measure of an event A, denoted by: $b(A) \doteq \sum_{\emptyset \subseteq B \subseteq A} m(B)$. Here we analyse the geometric behavior of the latter, in which case $\emptyset$ is not treated as an exception: the case of belief measures is left to future work. As $b(\Theta) = 1$, as usual, we neglect the related coordinate and represent believability functions as points of a Cartesian space of dimension $|2^\Theta| - 1$ (as $\emptyset$ cannot be ignored anymore).

Conjunctive combination on the binary frame. In the case of a binary frame, the conjunctive combination of two belief functions Bel_1 and Bel_2 yields:

$$
\begin{aligned}
m_{\bigcirc}(\emptyset) &= m_1(\emptyset) + m_2(\emptyset) - m_1(\emptyset)m_2(\emptyset) + m_1(x)m_2(y) + m_1(y)m_2(x), \\
m_{\bigcirc}(x) &= m_1(x)(m_2(x) + m_2(\Theta)) + m_1(\Theta)m_2(x), \\
m_{\bigcirc}(y) &= m_1(y)(m_2(y) + m_2(\Theta)) + m_1(\Theta)m_2(y), \\
m_{\bigcirc}(\Theta) &= m_1(\Theta)m_2(\Theta).
\end{aligned}
\tag{7}
$$

Conditional subspace for conjunctive combination. The global behaviour of $\bigcirc$ in the binary (unnormalised) case can then be understood in terms of its conditional subspace, this time in $\mathbb{R}^3$. We have, after denoting $b = [b(\emptyset), b(x), b(y)]'$:

$$
\begin{aligned}
b \bigcirc b_\emptyset &= b_\emptyset = [1,1,1]'; \\
b \bigcirc b_x &= (m(\emptyset) + m(y))b_\emptyset + (m(x) + m(\Theta))b_x \\
&= [m(\emptyset) + m(y), 1, m(\emptyset) + m(y)]' = b(y)b_\emptyset + (1 - b(y))b_x; \\
b \bigcirc b_y &= (m(\emptyset) + m(x))b_\emptyset + (m(y) + m(\Theta))b_y \\
&= [m(\emptyset) + m(x), m(\emptyset) + m(x), 1]' = b(x)b_\emptyset + (1 - b(x))b_y; \\
b \bigcirc b_\Theta &= b,
\end{aligned}
\tag{8}
$$

as $b_x = [0,1,0]'$, $b_y = [0,0,1]'$, $b_\emptyset = [1,1,1]'$ and $b_\Theta = [0,0,0]'$. From (8), we can note that the vertex $b \bigcirc b_x$ belongs to the line joining $b_\emptyset$ and b_x, with affine coordinate given by the believability assigned by b to the other outcome y. Similarly, the vertex $b \bigcirc b_y$ belongs to the line joining $b_\emptyset$ and b_y, with coordinate given by the believability assigned by b to outcome x (see Figure 4).

Conditional subspace for disjunctive combination. As for the disjunctive combination, it is easy to see that in the unnormalised case we get: $b \bigcirc b_\Theta = b_\Theta$, $b \bigcirc b_x = b(x)b_x + (1 - b(x))b_\Theta$, $b \bigcirc b_\emptyset = b$, $b \bigcirc b_y = b(y)b_y + (1 - b(y))b_\Theta$, so that the conditional subspace is as in Figure 4. Note that, in the unnormalised case, there is a unit element to $\bigcirc$, namely $b_\emptyset$. We can observe a clear symmetry between the subspaces induced by disjunctive and conjunctive combination.

6 Conclusions

A number of questions remain open after this preliminary geometric analysis of other combination rules on binary spaces, and its extension to the case of unnormalised belief functions. In particular, the general pointwise geometric behaviour of disjunctive combination, in both the normalised and unnormalised case, needs to be understood. The question of whether disjunctive combination commutes with affine combination in general belief spaces remains open. A dual

query concerns the conjuctive rule, as the alter ego of Dempster's rule in the unnormalised case. The general pointwise geometric behaviour of conjunctive and disjunctive combinations in the unnormalised case, as well as the complete description of their conditional subspaces, will also be subject of future work. The bold and cautious rules, which are also inherently defined for unnormalised belief functions, will also be analysed.
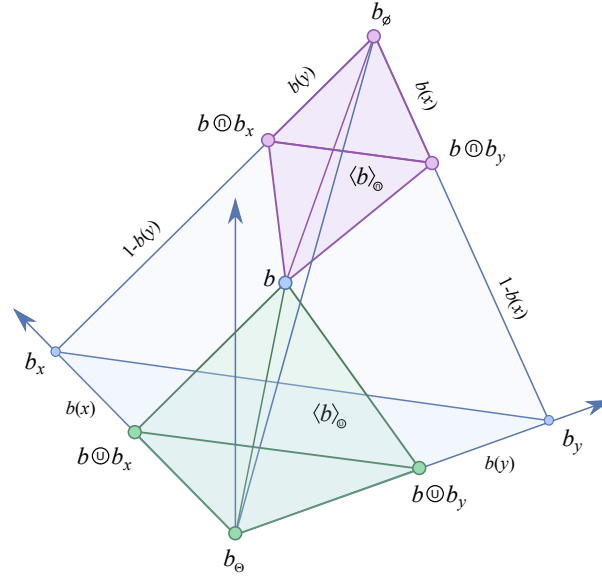
Fig. 4. Conditional subspaces induced by ⋒ and ⋓ in a binary frame, for the case of unnormalised belief functions.

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